LOCOMOTOR SKILLS: Estimation Activity

Skill	Y/N Performance Criteria		25	50
RUN	1. Brief period where both feet are off the ground	Trial 1		
	2. Arms in opposition to legs, elbows bent	-		
	3. Narrow foot placement near or on a line (not flat footed)	Trial 2		
	4. Nonsupport leg bent approximately 90 degrees (close to buttocks)	Trial 3		
		Trial 4		
GALLOP	 Step forward with the lead foot followed by a step with the trailing foot to a position adjacent to or behind the lead foot 			
	2. Brief period where both feet are off the ground	1		
	3. Arms bent and lifted to waist level	2		
		3		
	4. Maintain a rhythmic pattern for four consecutive gallops	4		
НОР	1. Foot of nonsupport leg is bent and carried back of the body	1		
	2. Nonsupport leg swings in pendular fashion to produce force			
	3. Arms bent at elbows and swing forward on take off	2		
	4. Takes off and lands three consecutive times on non-preferred foot	3		
		4		
	Takes off and lands three consecutive times on preferred foot			
LEAP	1. Take off on one foot and land on the opposite foot			
	2. A period where both feet are off the ground (longer than running)			
	3. Forward reach with arm opposite the lead foot			
HORIZONTAL	1. Preparatory movement includes flexion of both knees with arms			
JUMP	extended behind the body			
	2. Arms extend forcefully forward and upward, reaching full extension			
	above head			
	3. Take off and land on both feet simultaneously			
	4. Arms are brought downward during landing			
SKIP	1. A rhythmical repetition of the step-hop on alternate feet			
	2. Foot of nonsupport leg carried near surface during hop			
	3. Arms alternately moving in opposition to legs at about waist level			
SLIDE	1. Body turned sideways to desired direction of travel			
	2. A step sideways followed by a slide of the trailing foot to a point next to the lead foot			
	3. A min. of four continuous step-slide cycles to the right			
	4. A min. of four continuous step-slide cycles to the left			

TGMD: OBJECT CONTROL SKILLS

Skill	Performance Criteria	Complete
TWO-HAND STRIKE	1. Dominate hand grips bat above nondominate hand	
	2. Nondominate side of body faces the tosser (feet parallel)	
	3. Hip and spine rotation	
	4. Weight is transferred by stepping with front foot	
	5. Bat contacts ball	
STATIONARY Dribble	1. Contact ball with one hand at about hip height	
	2. Pushes ball with fingers (not a slap)	
	3. Ball contacts floor in front of (or outside of) foot on the side of hand being used	
	4. Maintains control of ball for 4 consecutive bounces without moving	
САТСН	 Preparation phase where elbows are flexed and hands are in front of body 	
	2. Arms extend in preparation for ball contact	
	3. Ball is caught and controlled by hands only	
KICK	1. Rapid continuous approach to the ball	
	2. Elongated stride into ball with trunk inclined backward during ball	
	contact 3. Non kicking foot even or slightly in back of the ball	
	4. Kicks ball with preferred foot, shoelaces or toe	
OVERHAND THROW	1. A downward arc of the throwing arm initiates the windup	
	2. Rotation of the hip and shoulder to a point where the nondominant side faces an imaginary target	
	3. Weight is transferred by stepping with the foot opposite the throwing hand	
	 Following-through beyond ball release diagonally across body toward side opposite throwing arm 	
UNDERHAND ROI	 LL 1. Preferreed hand swings down and back, reaching behind the trunk while chest faces cones 2. Strides forward with foot opposite the preferred hand hand towards the cones 3. Bends kness to lower body 	
	4. Releases ball close to the floor so ball does not bounce more than 4 inches high	